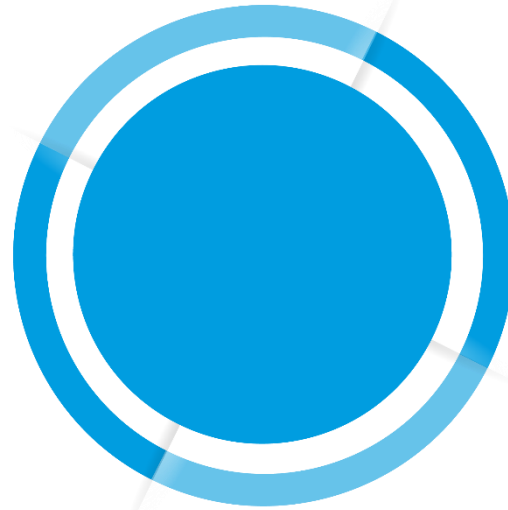


3D Simulation in NGSolve

SyMSpace Days 2024

Armin Fohler

NGSolve



SyMSpace Interface

Applikationen



NGSolve

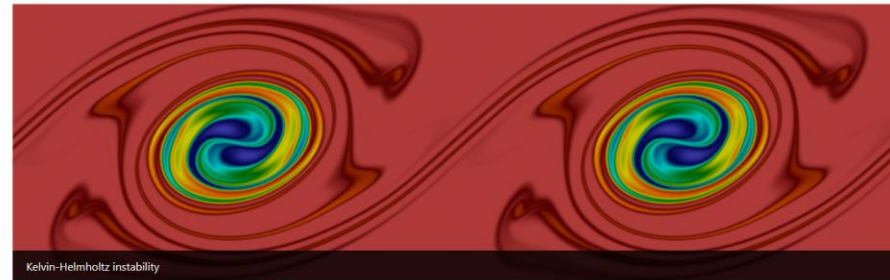
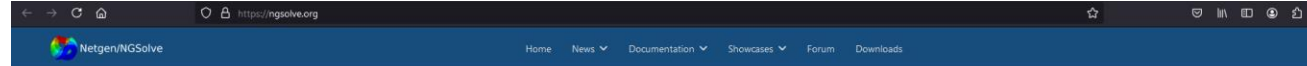


NGSolve

- High performance multiphysics finite element software
- Problembeschreibung über mathematische Formulierung
- Python-Interface
- Entwickelt an der TU Wien
- Aktive Community

Homepage

<https://ngsolve.org/>



Kelvin-Helmholtz instability



Netgen/NGSolve is a high performance multiphysics finite element software. It is widely used to analyze models from solid mechanics, fluid dynamics and electromagnetics. Due to its flexible Python interface new physical equations and solution algorithms can be implemented easily.



All in one

Seamless integration from geometric modeling, mesh generation, numerical simulation to visualization



Flexible

Mathematical description of variational formulation allows coupling of arbitrary physical models



Accurate

Cutting edge numerical techniques: high order, vectorial, mixed and discontinuous, Galerkin methods



Efficient

Robust preconditioners adapted to function spaces and differential equations



High Performance

Parallel compute core written in modern C++ combined with Boost libraries for Python interface



Open

Open source based on the LGPL license, extendable by C++ modules and Python modules



SyMSpace Interface

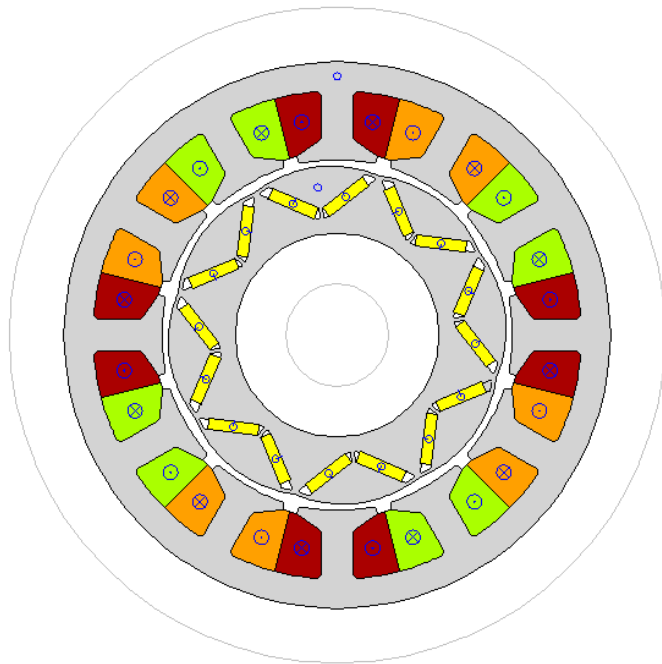
2

SyMSpace/NGSolve Interface



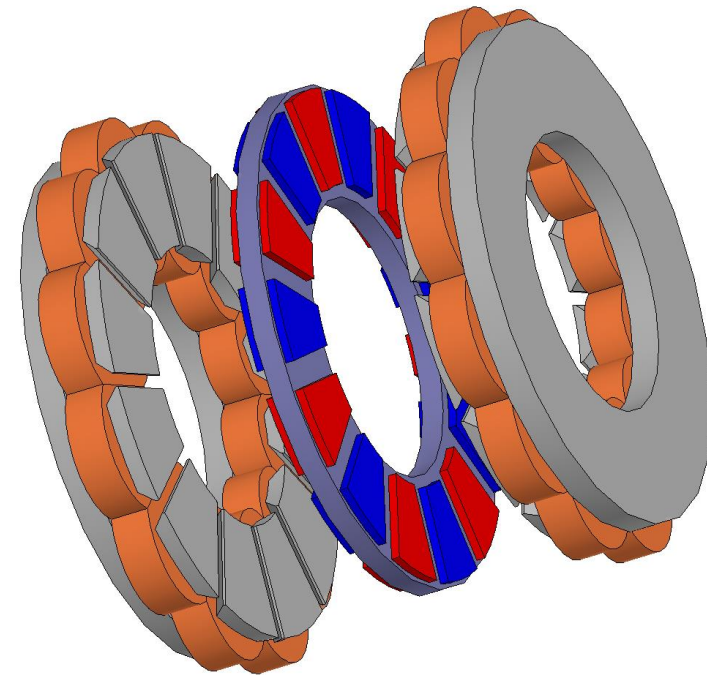
3D Aspects for Electrical Machine Simulations

Radial Flux Machine



- Magnet-Losses
- Endwinding Inductances

Axial Flux Machine

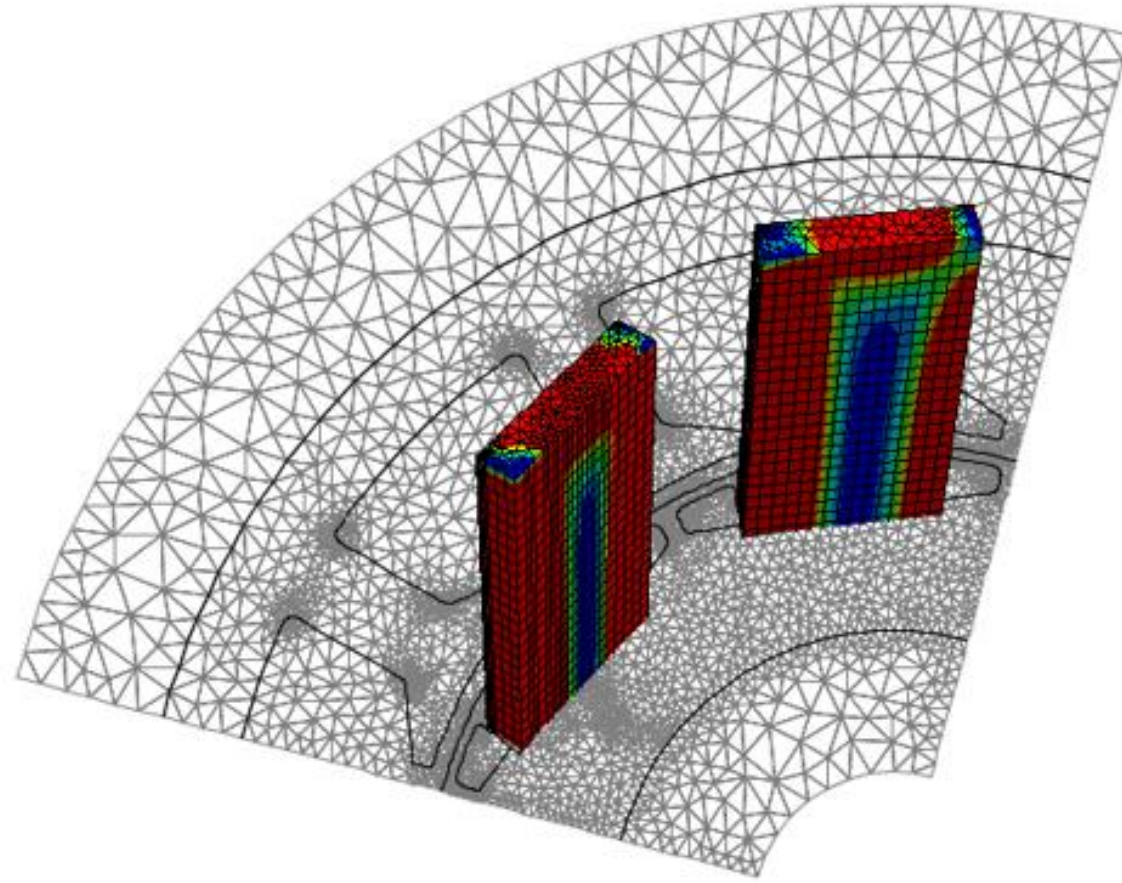




Applikationen

3

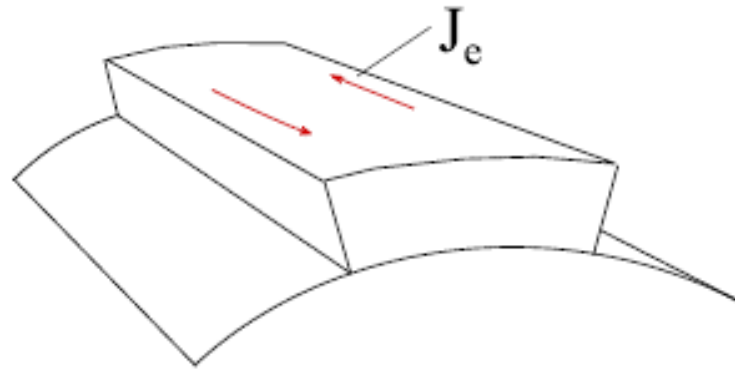
Magnet-Verlust Abschätzung



Herangehensweise

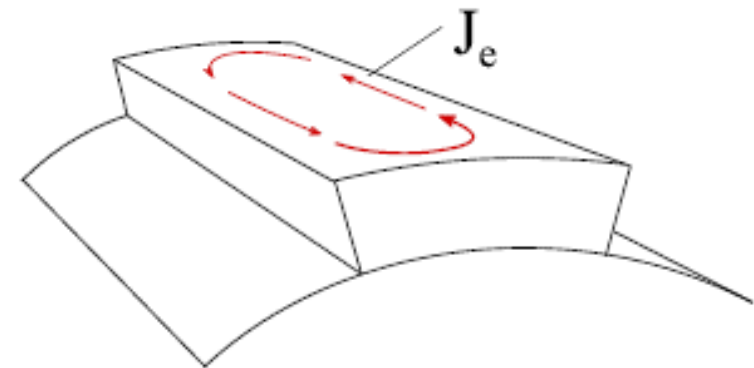
[Carpenter1977]

2D Abschätzung



- Schnelle Berechnung
- Vernachlässigt Rückwirkung
- Magnet ‚unendlich‘-lange modelliert

2D/3D Kopplung



- Beinhaltet Endeffekte
- Vernachlässigt Rückwirkung

Model: Eddy Current Problem

Aus

$$\begin{aligned}\operatorname{curl} E &= -\frac{\partial B}{\partial t} \\ J &= \sigma E \\ \operatorname{div} J = 0 &\rightarrow J = \operatorname{curl} T\end{aligned}$$

Resultiert

$$\operatorname{curl} \frac{1}{\sigma} \operatorname{curl} T = -\frac{\partial B}{\partial t}$$

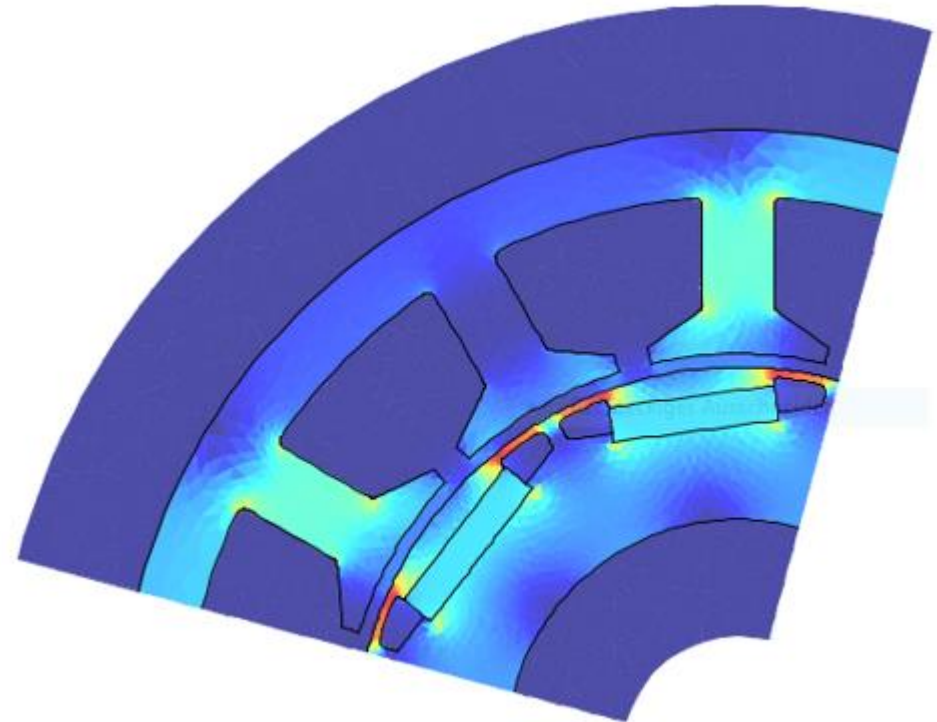
Mit

E	elektrische Feldstärke
B	magnetische Flussdichte
J	elektrische Stromdichte
σ	elektrische Leitfähigkeit
T	elektrisches Vektorpotential

Implementierung I

- 2D Motor Simulation in FEMM42
- Export des Magnet-Meshs und B-Feldes
- Berechnung von $-\frac{\partial B}{\partial t}$
- Extrusion des Meshs
- Lösung von

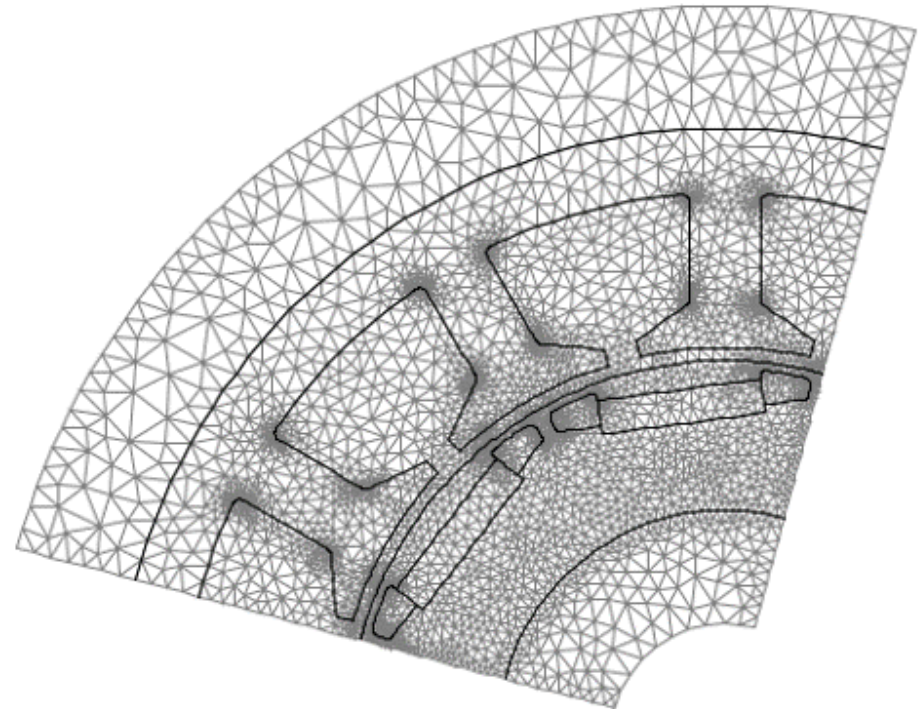
$$\operatorname{curl} \frac{1}{\sigma} \operatorname{curl} T = -\frac{\partial B}{\partial t}$$



Implementierung II

- 2D Motor Simulation in FEMM42
- Export des Magnet-Meshs und B-Feldes
- Berechnung von $-\frac{\partial B}{\partial t}$
- Extrusion des Meshs
- Lösung von

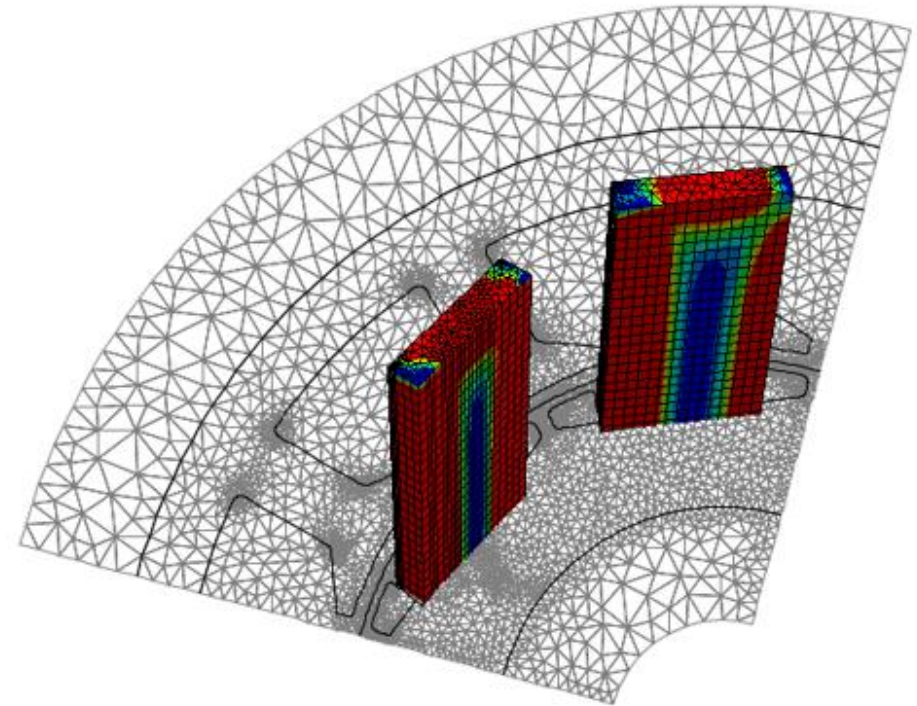
$$\text{curl} \frac{1}{\sigma} \text{curl} T = -\frac{\partial B}{\partial t}$$



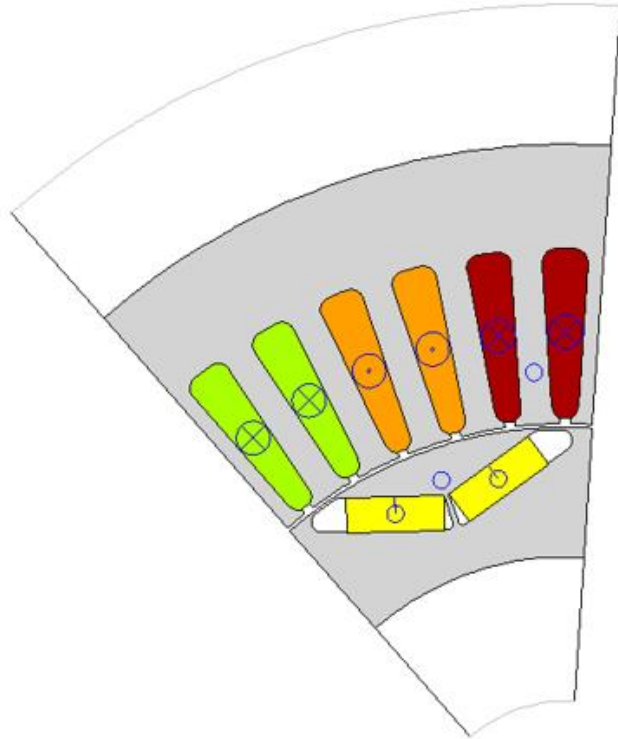
Implementierung II

- 2D Motor Simulation in FEMM42
- Export des Magnet-Meshs und B-Feldes
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- Extrusion des Meshs
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$$\operatorname{curl} \frac{1}{\sigma} \operatorname{curl} T = -\frac{\partial B}{\partial t}$$



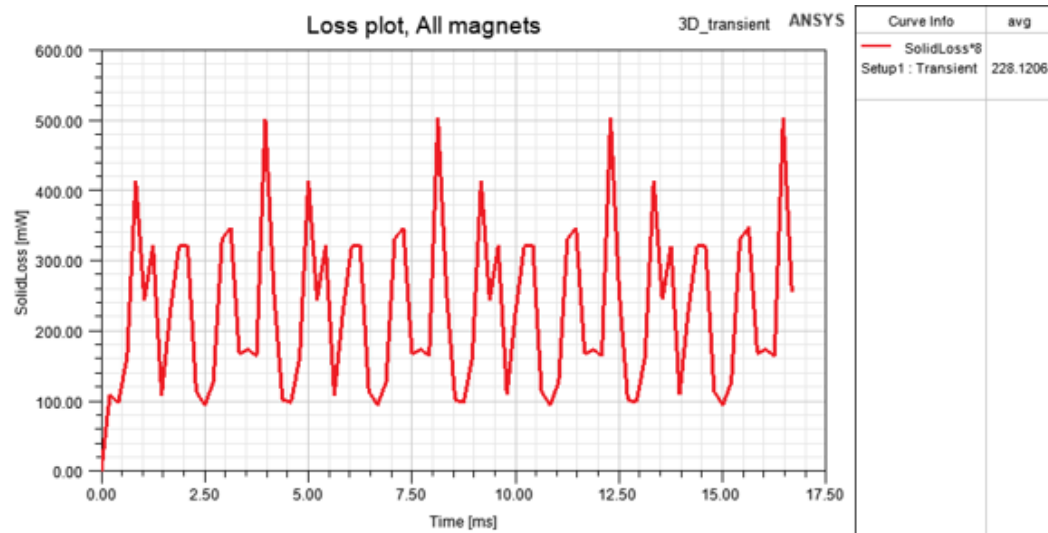
Example: Prius



- Rpm = 1800
- Sigma = 666666.6666
- Simulation length = $\pi/8$
- Magnet length = 84.0 mm (not segmented)

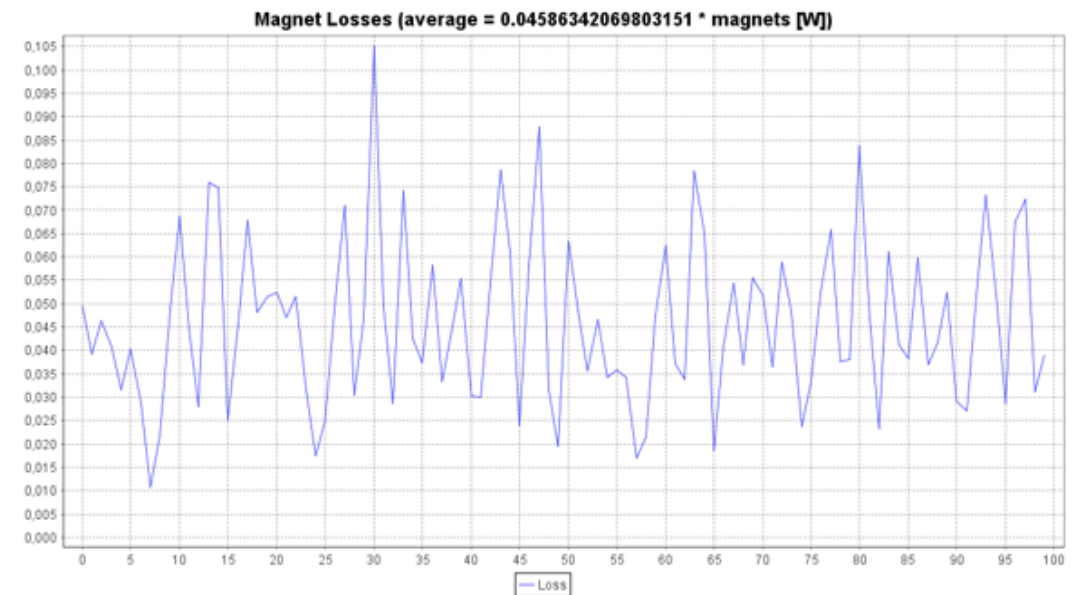
Vergleich: Prius

Anslys Maxwell Simulation



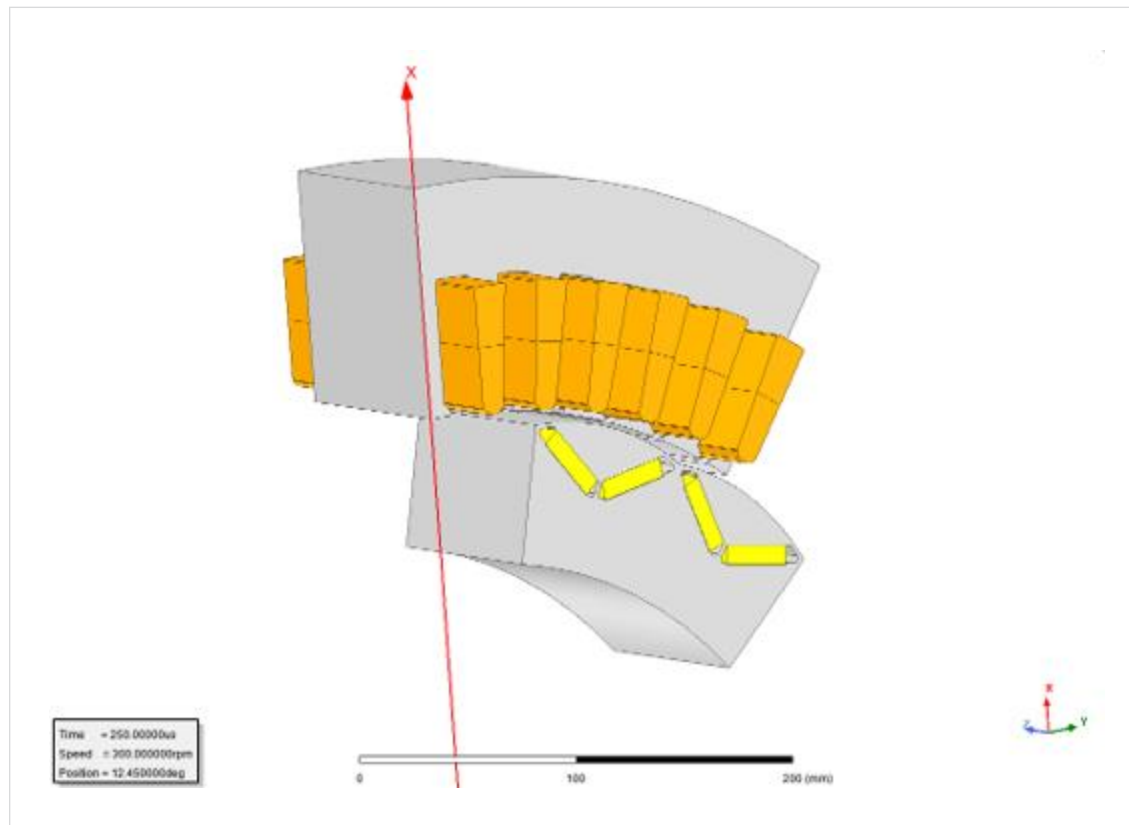
Maxwell avg. losses: 0.228 W

NGSolve Simulation



NGSolve avg. losses: 0.367 W

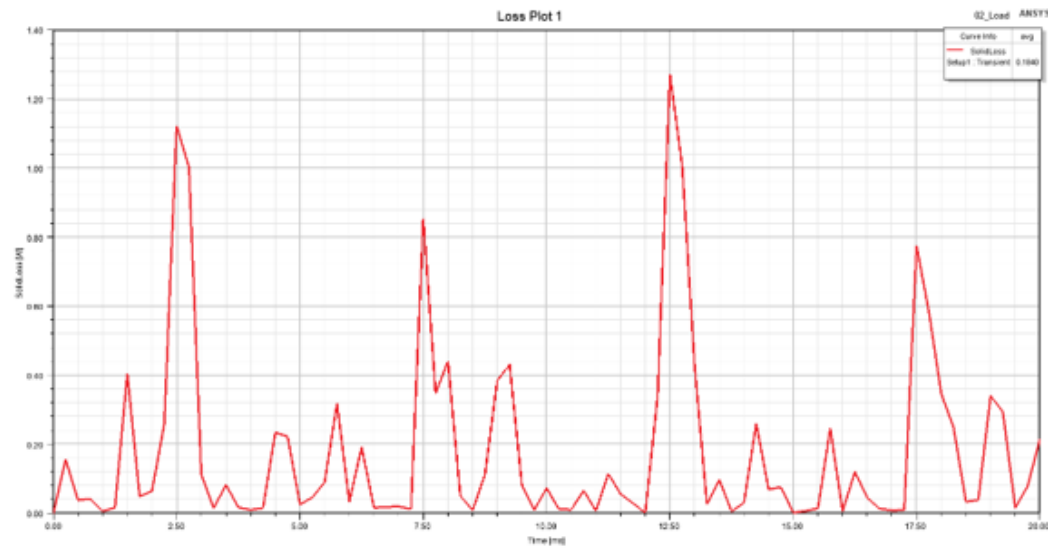
Example: Generator



- Rpm = 300
- Sigma = 666666.6666
- 4 Magnet Segments

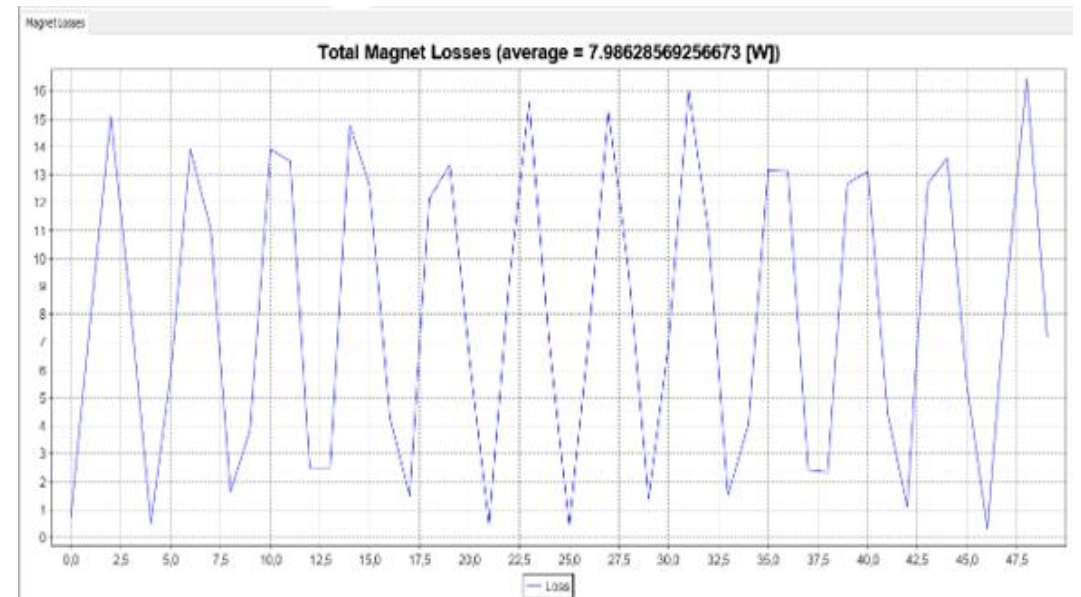
Vergleich: Generator

Ansys Maxwell Simulation



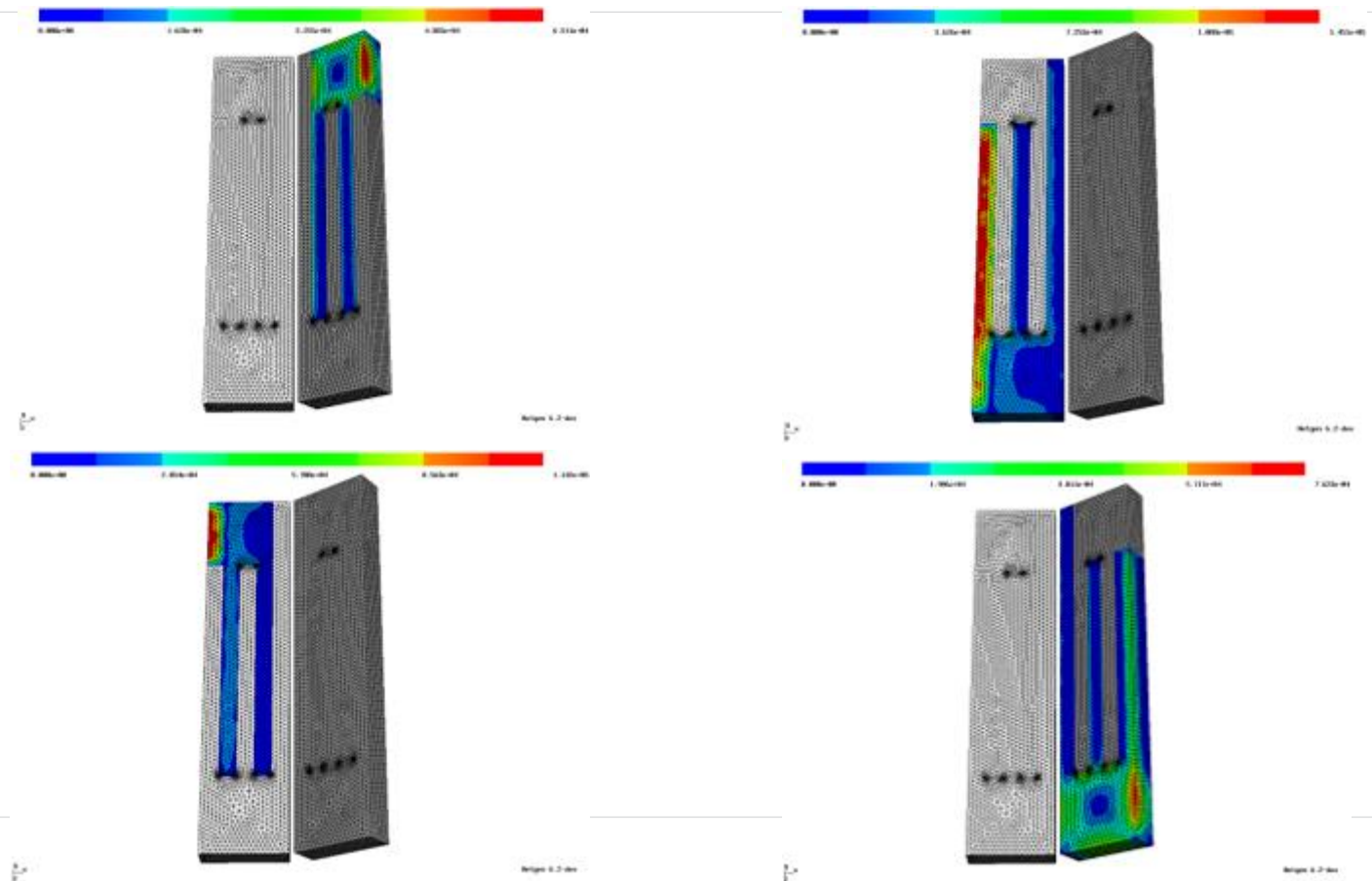
Maxwell avg. losses: 7.36 W

NGSolve Simulation

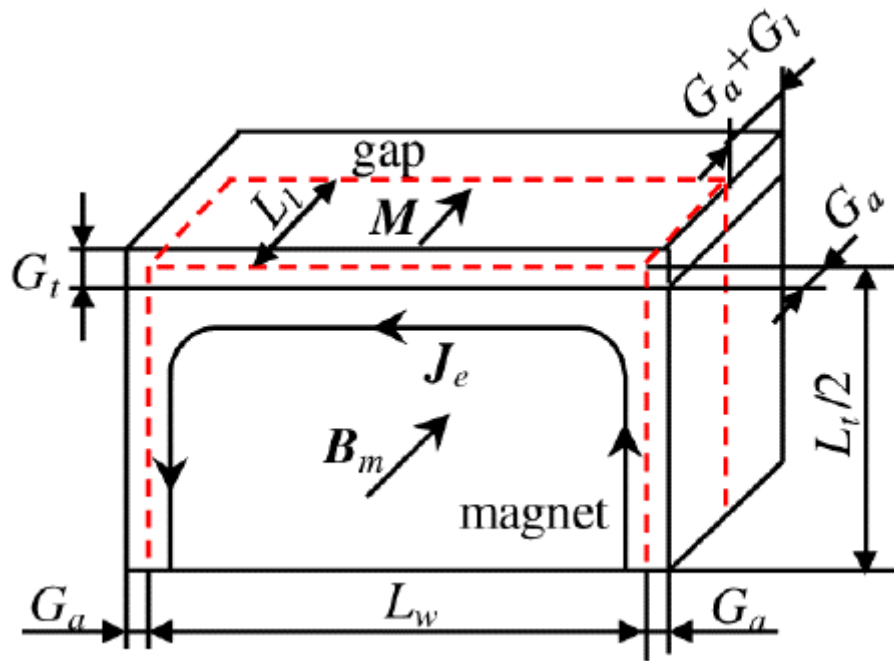


NGSolve avg. losses: 7.98 W

- Segmentierung in der x-y-Ebene
- Snakeline Segmentierung



Extensions



- Berücksichtigung der Rückwirkung [Okitsu2009]

Referenzen

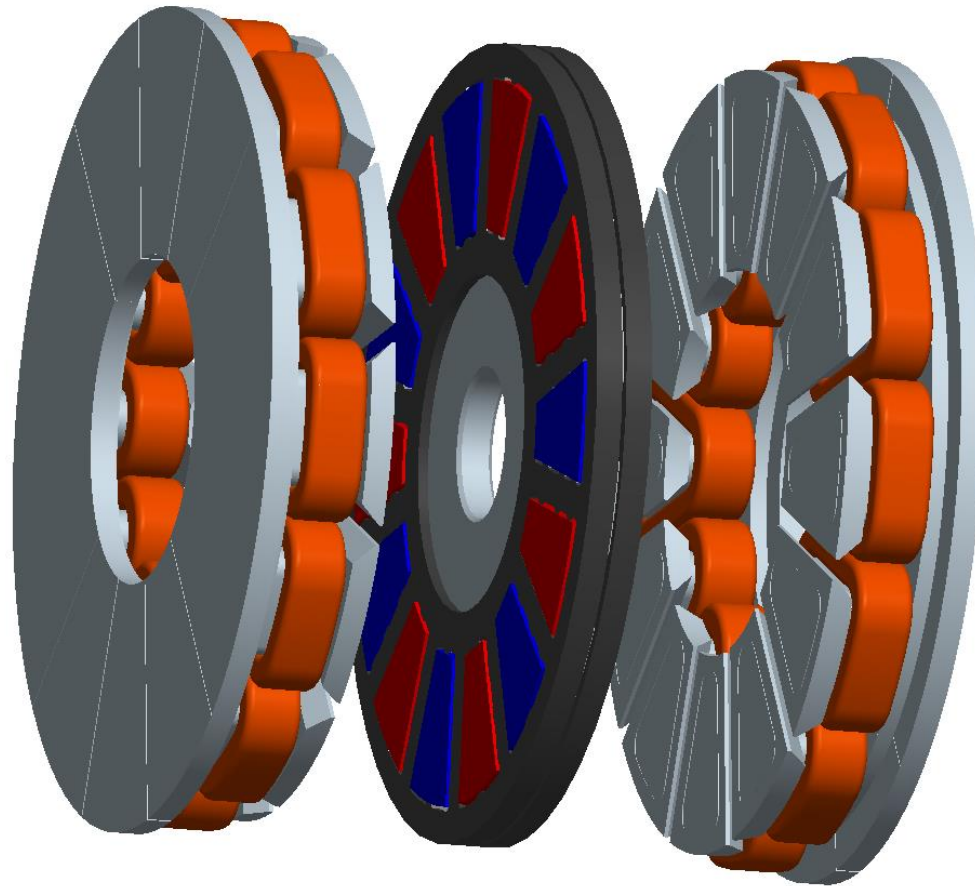
[Carpenter1977]: Carpenter, C.J.: 'Comparison of alternative formulations of 3-dimensional magnetic-field and eddy-current problems at power frequencies', Proceedings of the Institution of Electrical Engineers, 1977, 124, (11), p. 1026-1034.

[Yamazaki2009]: K. Yamazaki and Y. Kanou, "Rotor Loss Analysis of Interior Permanent Magnet Motors Using Combination of 2-D and 3-D Finite Element Method," in IEEE Transactions on Magnetics, vol. 45, no. 3, pp. 1772-1775, March 2009.

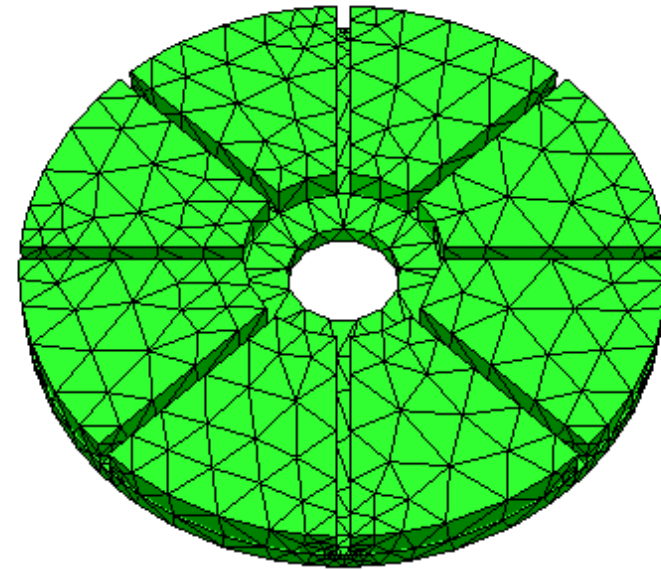
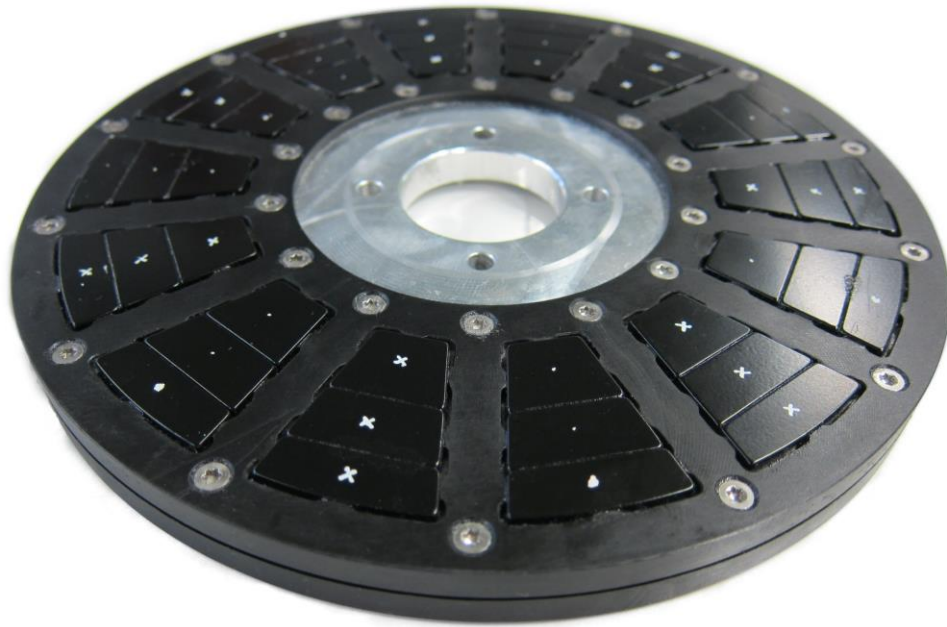
[Okitsu2009]: T. Okitsu, D. Matsubishi and K. Muramatsu, "Method for Evaluating the Eddy Current Loss of a Permanent Magnet in a PM Motor Driven by an Inverter Power Supply Using Coupled 2-D and 3-D Finite Element Analyses," in IEEE Transactions on Magnetics, vol. 45, no. 10, pp. 4574-4577, Oct. 2009.

[Steentjes2015]: S. Steentjes, S. Boehmer and K. Hameyer, "Permanent Magnet Eddy-Current Losses in 2-D FEM Simulations of Electrical Machines," in IEEE Transactions on Magnetics, vol. 51, no. 3, pp. 1-4, March 2015.

Axial Flux Machine

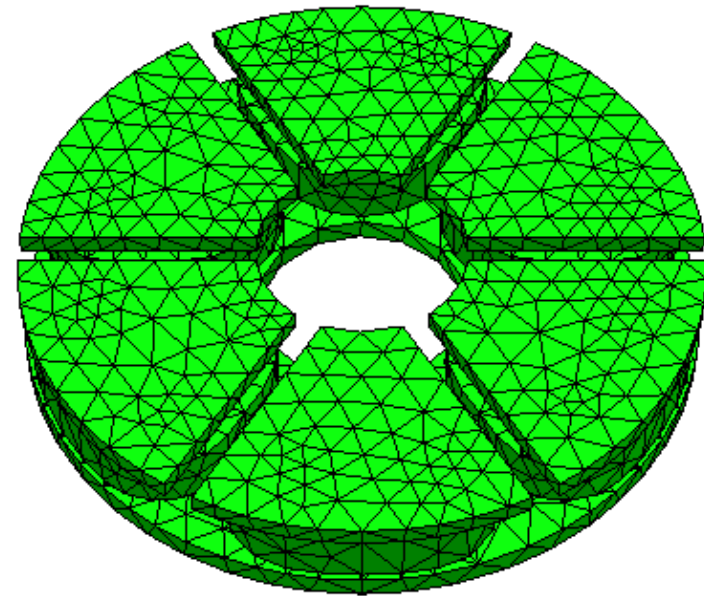


Geometrie: Rotor

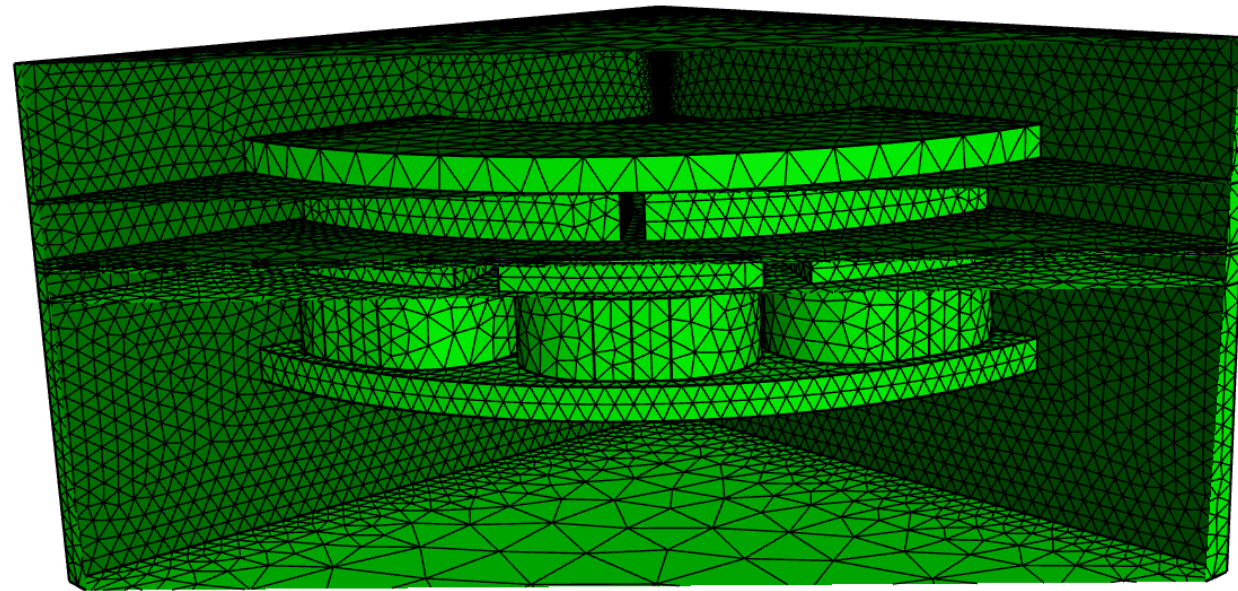


Netgen 6.2-dev

Geometrie: Stator



Geomtrie



Nitsche Mortaring

Find $\mathbf{u} \in V$ and $\lambda \in \Phi$ such that

$$a(\mathbf{u}, \mathbf{v}, \lambda, \psi) = \langle f, \mathbf{v} \rangle \quad \forall \mathbf{v} \in V \text{ and } \psi \in \Phi$$

where $V = \{\mathbf{w} \in H(\text{curl}, \Omega_R) \cap H(\text{curl}, \Omega_S) \mid \mathbf{w} = 0 \text{ on } \partial\Omega\}$
and $\Phi = L^2(\Omega_R \cap \Omega_S)$

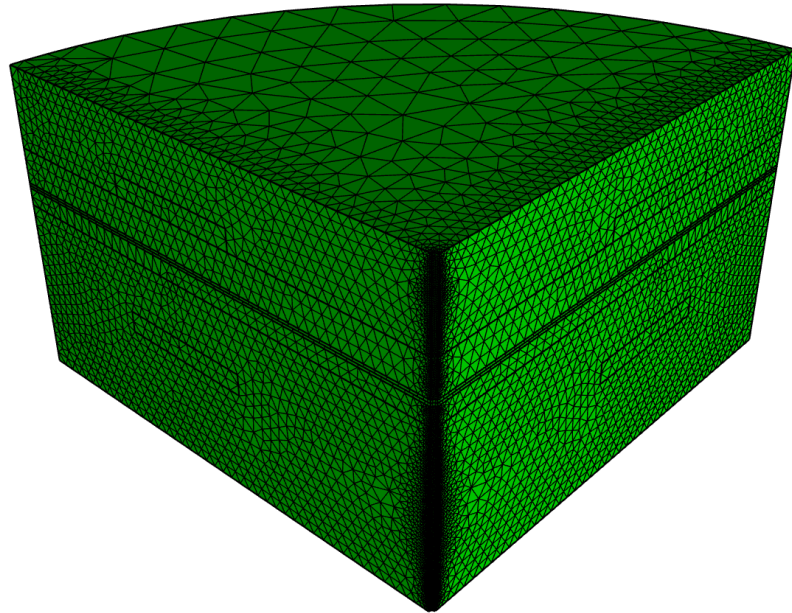
Semilinear Form

$$\begin{aligned} a(\mathbf{u}, \mathbf{v}, \lambda, \psi) = & \sum_{i \in \{R, S\}} \int_{\Omega_i} (\nu(\operatorname{curl} \mathbf{u}) \cdot (\operatorname{curl} \mathbf{v}) + \kappa \mathbf{u} \cdot \mathbf{v}) \, dx \\ & + \int_{\Gamma_i} \nu \operatorname{curl} \mathbf{u} \cdot ((\mathbf{v} - \psi) \times \mathbf{n}) \, ds \\ & + \int_{\Gamma_i} \nu \operatorname{curl} \mathbf{v} \cdot ((\mathbf{u} - \lambda) \times \mathbf{n}) \, ds \\ & + \frac{\alpha p^2}{h} \int_{\Gamma_i} \nu ((\mathbf{u} - \lambda) \times \mathbf{n}) \cdot ((\mathbf{v} - \psi) \times \mathbf{n}) \, ds \end{aligned}$$

Linear Form

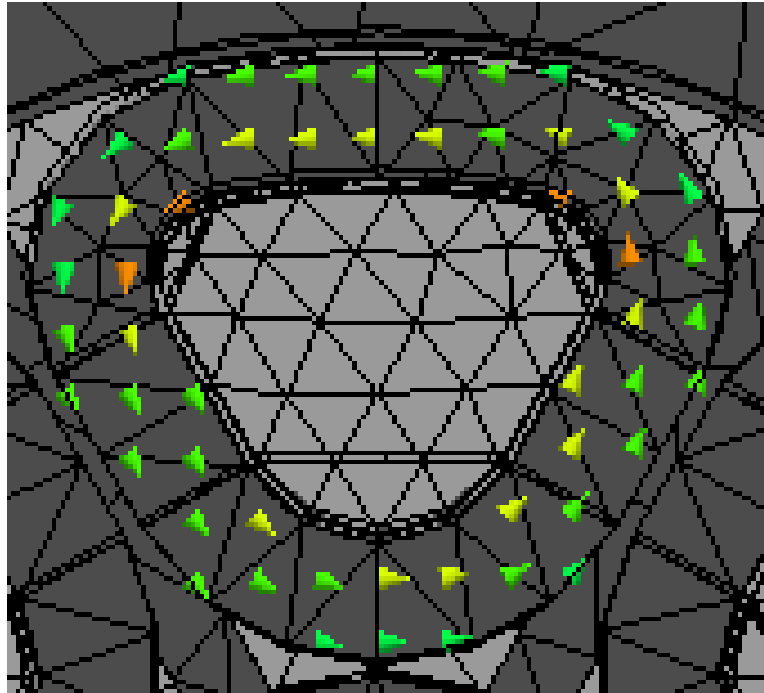
$$\langle f, v \rangle = \sum_{i \in \{R, S\}} \int_{\Omega_i} (J \cdot v + M \cdot \text{curl } v) dx$$

Implementierung I



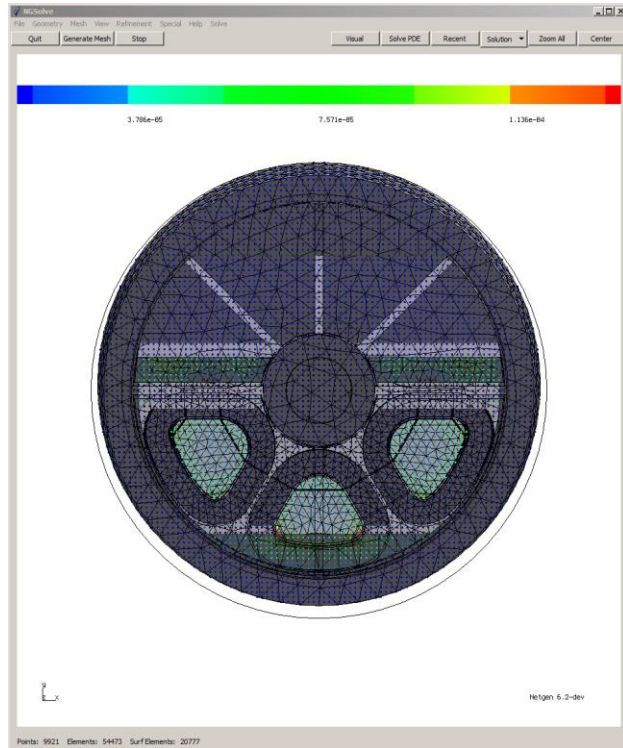
- Geometrien fusionieren
- Berechnung der Bestromungsfelder in den Spulen
- Berechnung des Vektorpotentials
- Bestimmung von Drehmoment und Verkettungen

Implementierung II



- Geometrien fusionieren
- Berechnung der Bestromungsfelder in den Spulen
- Berechnung des Vektorpotentials
- Bestimmung von Drehmoment und Verketteten Flüssen

Implementierung III

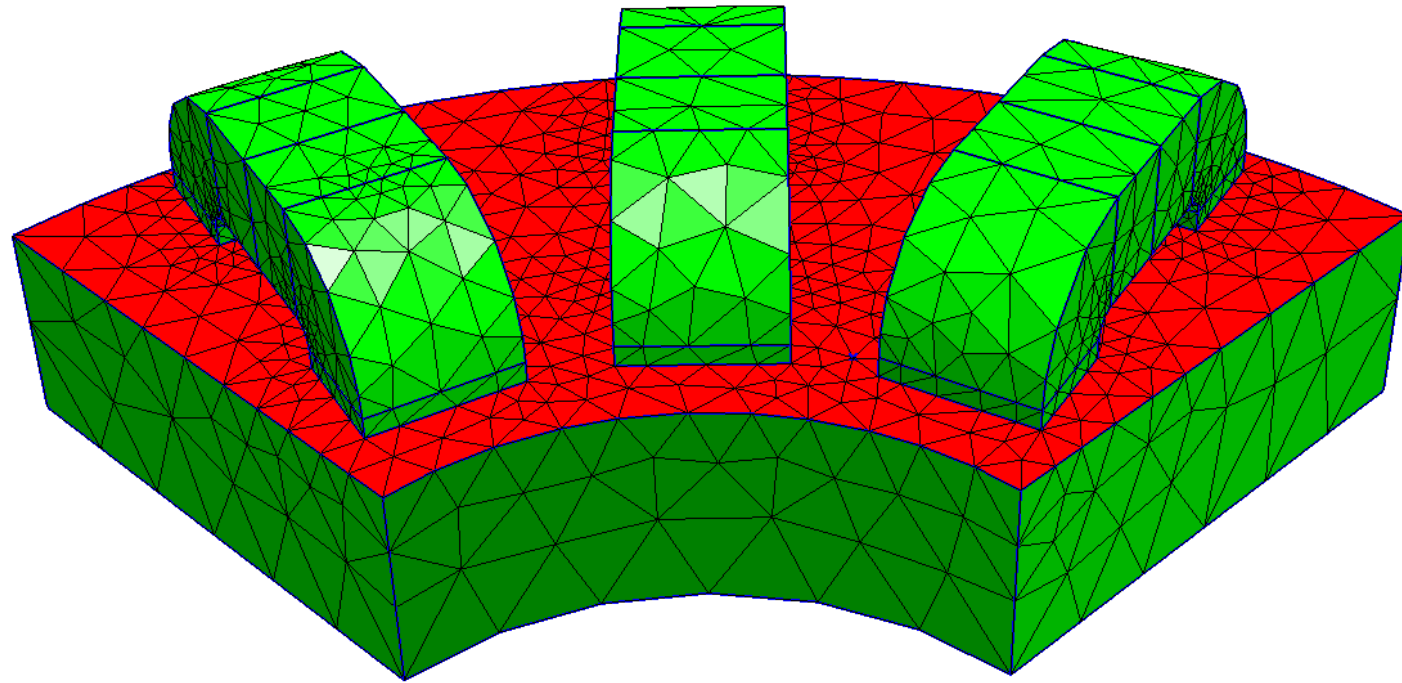


- Geometrien fusionieren
- Berechnung der Bestromungsfelder in den Spulen
- Berechnung des Vektorpotentials
- Bestimmung von Drehmoment und Verkettungen

Referenzen

[Hollaus2010]: Hollaus, K., Feldengut, D., Schöberl, J., Wabro, M., and Omeragic, D. (2010, July). Nitsche-type mortaring for Maxwell's equations. In Progress In Electromagnetics Research Symposium Proceedings (Cambridge, USA) (pp. 397-402).

Wickelkopf-Induktivitäten



Haben Sie noch
Fragen?